





MUIRHEAD AEROSPACE Synchros



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Muirhead Aerospace

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Synchros are used to transmit angular data electrically from one location to another where a high degree of accuracy is required. They are essentially variable transformers in which the coupling between windings varies with the rotor position relative to the stator. Several different types are produced to suit particular applications and whilst their external appearance is similar, the internal construction varies to optimise the units' functional requirements. Muirhead's pedigree and capability in the field of Synchros will ensure the most demanding specifications are met. Typical applications include remote positioning of low torque mechanisms, remote control by servo motor driven mechanism, remote digital measurement of angle via a suitable signal converter, remote pointer indication of angular position.

Control Synchros

The design principle of a Control Synchro is to minimise errors in the output signal due to current loading, magnetic non-linearity and temperature rise, by the use of high impedance windings and special attention to the magnetic circuits. The Control Transformer which provides the error signal to a servo amplifier, can be considered a 'null detector and it is most often used in this way. However the 'null' is never zero due to residual voltages. This is due to stray couplings within the laminated stator that result in an in-phase voltage, a quadrature voltage, both at fundamental frequency, plus a number of harmonics. These residual voltage levels are quoted in the performance data tables for each unit.

Differential Transmitters

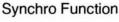
It is sometimes necessary to add or subtract additional information from a Synchro Chain and Differential Transmitters serve this purpose. They are similar in construction to the other elements except for a 3-phase winding on the rotor.

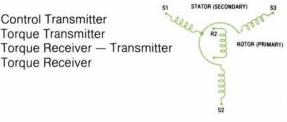
Torque Synchros

The Torque Synchro is designed to provide a light torque output without additional servo components. Current is fed to both the Transmitter and the Receiver from the same source and the winding impedance values are considerably lower than the equivalent control elements. Torque is generated as a result of the interaction of the stator and rotor fields in the receiver which drives the rotor of the Receiver into alignment with that of the Transmitter. The torque / misalignment curve takes sinusoidal form through 360 degrees with maximum values of opposite polarity at 90 and 270 degrees.

Winding Configuration Hardware Information

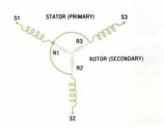
Winding Configuration



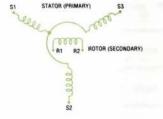


Control Differential Transmitter

Torque Differential Transmitter

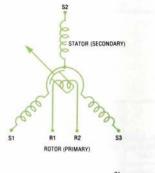


Control Transformer

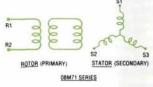


Specialised Synchros

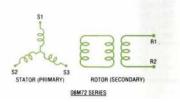
Indicating Receiver (See page 15)



Brushless Control Transmitter (See page 14)



Brushless Control Transformer (See page 14)



Tandem (See page 14) PICK-OFF STATOR RED WHITE BLACK/WHITE BLACK/WHITE RED/WHITE CONTROL TRANSFORMER ROTOR YELLOW YELLOW YELLOW YELLOW YELLOW YELLOW YELLOW YELLOW

Note

Winding configurations are shown at zero shaft positions viewed from the terminal end. For example, in the wiring configuration for the Control Transmitter, voltage (R1 R2) is approximately in phase with voltage (S2 S1) and voltage (S3 S2).

Damping flywheels are fitted to size 15, 18, and 23 Torque Receivers/Transmitters. For size 08 and 11, damping is achieved by the use of high viscosity bearings.

Mounting Hardware

Each synchro (except size 23) is supplied with a set of three mounting clamps, and where required, shaft nut and washers, together with terminal tags. In addition, Muirhead Vactric can supply at extra cost a variety of hardware. Full details are described in the Mounting Information leaflet. A reference table below shows some of the available choices.

PINION AND SOCKE Please note that thes	and the same of	Contract of the second	100	separa	tely.
Order Ref		Fr	ame S	ize	
	08	11	15	18	23
Pinion wrenches F500/8 & F500/9		*	*	*	*
Socket wrench F500/21	*				
Socket wrench F500/51		*	*	*	
Socket wrench F500/52					*

* Available

METRIC CONVERSION FACTORS

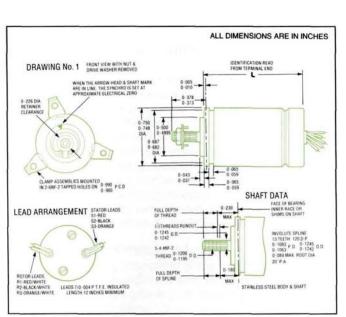
Torque 1 gcm = 0.098 mNmTorque 1 gcm = $1.389 \times 10^{-2} \text{ oz in}$ Torque 1 oz. in. = 72.01 g cmInertia 1 oz. in² = $1.829 \times 10^2 \text{ g cm}^2$ Weight 1 oz. = 28.349 gDistance 1 in. = 25.4 mm



26V 400 Hz EL 1790

STANDARD HARDWARE SUPPLIED WITH EACH INSTRUMENT Item Type No Detail RefClamp Assembly F500/33 A+B Shaft Nut F500/37 A† Drive Washer (Aluminium) F500/38A A†

AMBIENT TEMPERATURE RANGE: -65°C + 150°C Weight 50g (1.75 oz) Rotor Inertia 1.1g cm² (0.006 oz in²) Friction Torque 2.9g cm (0.04 oz in) (Not applicable to Torque Receivers)



						PRIMAR	Y				
SYNCHRO Function	Drawing & Hardware Detail Ref	TYPE DESIGNATION Muirhead	NATO NUMBER 5990-99-	MILITARY SPECIFICATION	LENGTH (Dim·L) in inches max »	TERMINALS	RATED VOLTS Volts	Amps max	NO LOAD INPUT Watts max	Ohms nom	D.C. RESISTANCE
CONTROL TRANSFORMER	1-A	26V08CX4(B1) 08M1C1	947-3051	EL 1790	1-350	R1 R2 (ROTOR)	26	26	0.111	0.95	60
CONTROL TRANSFORMER	1-A	26V08CT4(B1) 08M2C1	947-3052	EL 1790	1-350	S1 S2 S3 (STATOR)	11-8	10-2	0 · 137	0 · 47	28
TORQUE RECEIVER TRANSMITTER	1-A	08M4A1	520-8549	_	1-350	R1 R2 (ROTOR)	26	26	0-3	3.2	26

				DESCRIPTION						PRIMAR	Y		
SYNCRO FUNCTION	Drawing & Hardware Detail Ref	TYP DESIGNA Military		NATO NUMBER 5990-99-	MILITAI SPECIFICA DEP STAN 59-27-2		LENGTH (Dim·L) in inches max	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANCE Ohms nom
CONTROL TRANSMITTERS	2a-A 2b-B 2d-B 2d-B	26V08CX4b * 26V08CX4C 26V08CX4c	08M1G1 08M51C1 08M1H1 08M1P1 08M1X1	972-7610 014-9848 519-5637 199-7029	— 078 DEF148/78 —	78A 78D 78C —	1-240	R1 R2 (ROTOR)	26 26 26 26 115	26 26 26 26 115	0·153 0·153 0·153 0·153 0·070	0·86 0·86 0·86 0·86 2·4	27 27 27 27 27 375
CONTROL DIFFERENTIAL TRANSMITTERS	2b-B	* 26V08CDX4C 26V08CDX4C	08M3N1 08M3D1	014-9850 519-5636	080 DEF148/80	80D 80C	1 · 240	S1 S2 S3 (STATOR)	11·8 11·8	10·2 10·2	0·108 0·108	0·3 0·3	25 25
CONTROL TRANSFORMERS	2a-A 2b-B 2b-B 2d.B	26V08CT4b * 26V08CT4C 26V08CT4c	08M2G1 08M52L1 08M2H1 08M2T1	972-7611 014-9849 519-5635 199-7030		79A 79D 79C	1.240	S1 S2 S3 (STATOR)	11 · 8 11 · 8 11 · 8 11 · 8	10·2 10·2 10·2 10·2	0·023 0·023 0·023 0·023	0·057 0·057 0·057 0·057	104 104 104 104
TORQUE RECEIVER TRANSMITTERS	2b-B 2c-A		08M4L1 08M4C1	712-0795		=	1.240	R1 R2 (ROTOR)	26 115	26 115	0·3 0·070	2 2·4	15·3 375

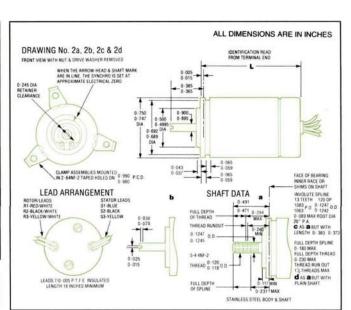


26V & 115V, 400Hz MIL-S-20708 DEF 148 DEF—STAN 59-27 PART 2

> AMBIENT TEMPERATURE RANGE: -55° C to + 125° C

* Denotes that the Synchro is on the British Qualified products list to specification DEF STAN 59-27 (PART 2). It is also certified as conforming to NATO Electronics Parts Recommendations for Standardisation of Synchros (N.E.P.R. No. 22) which refers to USA Specification MIL-S-20708C. It is preferred for military applications. Qualification is subject to renewal every four years.

Weight 45g (1·6 oz)
Rotor Inertia 0·8g cm² (0·0045 oz in²)
Friction Torque 2·9g cm (0·04 oz in)
(Not applicable to Torque Receivers)



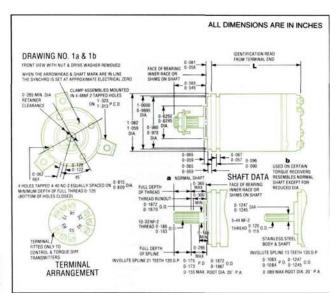
		SECONI	DARY								- 1	PERFORMANO	E				
TERMINALS		LOAD TPUT Phase lead	VOLTAGE GRADIENT Volts/deg	D.C RESISTANCE Ohms nom	NOMINA Zro	AL IMPEDENCE Zrs	E ohms Zso	Stator	ERROR mins Rotor	Receive	mV RESIDUAL r Fund Total	MINIMUM TORQUE GRADIENT g cm · oz in		XIMUM TINUOUS displace- ment deg	PULL-OUT TORQUE g cm	SYNCHE NISING TIME se 30° C 1	G
S1 S2 S3 (STATOR)	11-8	13		19	77+j270	137+j39	17+j49	10			20 40						
R1 R2 (ROTOR)	22-5	13-5	0.39	145	173+j564	253+j104	25+j93	10		MA	30 60						
S1 S2 S3 (STATOR)	11-8	18		8.5	36+j88		8+j20	10		120	Not Applicable	0.2 0.002	8 6	23	12	1	2

		SECOND	ARY									PERF	ORMANCE			
TERMINALS	NO LOAD OUTPUT Volts	Phase lead	VOLTAGE GRADIENT Volts/deg	D.C RESISTANCE Ohms nom	Zro	NOMINAL IN Zrs	IPEDANCE ohms Zso	z Zss	Stator	RROR mir Rotor	s Receiver	Fund	mV RESIDUAL Total	TORQUE GRADIENT Per degree g cm oz in	NIS	CHRO- SING Secs. C 175
COLUMN TO THE PARTY OF THE PART	11.8	8		10-8	32+j185	70+j23	9+j32	12-5+j2-7	7	7.4		20	30			
01 00 00	11-8	8		10.8	32+j185	70+j23	9+j32	12-5+j2-7	7			20	30			
S1 S2 S3	11.8	8		10-8	32+j185	70+j23	9+j32	12-5+j2-7	7			20	30			
(STATOR)	11-8	8		10-8	32+j185	70+j23	9+j32	12-5+j2-7	7			20	30			
9-5 13	11-8	12		6.5	500+j1890		6·5+j17	86+j1-8	7			30	30 30 60			
R1 R2 R3	11-8	9-5		34	33+j124	46+j14	24+j108	39+j14	7	7		20	30			
(ROTOR)	11-8	9.5		34	33+j124	46+j14	24+j108	39+j14	7 7	7		20	30 30			
1000	22.5	8.5	0.39	440	607+j2900	800+j300	100+j506	140+j53				25	30	-		
R1 R2	22-5	8-5	0-39	440	607+j2900	800+j300	100+j506	140+j53	7			25	30			
(ROTOR)	22.5	8.5	0.39	440	607+j2900	800+j300	100+j506	140+j53	7			25	30			
(NOTON)	22.5	8-5	0-39	440	607+j2900	800+j300	100+j506	140+j53	7			25	30		-01	
S1 S2 S3	11.8	10-5		6-5	20+j92		6-5+j17	86+j1-8	10		120	Nota	applicable	0-37 0-005	5 2	4
(STATOR)	11-8	12		6-5	500+j1890		6·5+j17	86+11-8	10		120		applicable	0.32 0.004	1 2	4



26V & 115V, 400Hz MIL-S-20708 DEF 148 DEF-STAN 59-27 (PART 2)

AMBIENT TEMPERATURE RANGE: -55° C to +125° C Weight 120g (4-2 oz)
Rotor Inertia 2-6g cm² (0-014 oz in²)
Friction Torque 3-6g cm (0-05 oz in)
(Not applicable to Torque Receivers)



			DE	ESCRIPTION						PRIMA	ARY		
SYNCHRO FUNCT:ON	Drawing & Hardware Detail Ref	TYPE DESIGNAT Military	10N Muirhead	NATO NUMBER 5990-99-	MILIT SPECIFI DEF STAN 59-27(2)		LENGTH (Dim·L) in inches max	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANCE Ohms nom
CONTROL TRANSMITTERS	1a-A	26V11CX4b	11M1G2	519-5600 580-7649	DEF 1	48/8 8A	1.732	R1 R2 (ROTOR)	26	26	0 - 130	0.56	21 - 2
THANSMITTENS	1a-C	* 26V11CX4C	11M1X2	014-9804	008	8C		(noton)	26	26	0.130	0.56	21-2
CONTROL DIFFERENTIAL	1a-A	26V11CDX4b	11M3B3	519-5602 580-9000	_ DEF	148/9 9A	1-789	S1 S2 S3	11-8	10.2	0 · 150	0.34	10-4
TRANSMITTERS	1a-C	* 26V11CDX4C	11M3M2	014-9805	009	9C		(STATOR)	11-8	10-2	0.150	0.34	10-4
CONTROL RANSFORMERS	1a-A	26V11CT4c	11M2G2	519-5595 972-6660	_ DEF	48/7 7A	1.732	S1 S2 S3	11.8	10.2	0.086	0-18	17-0
TRANSFORMERS	1a-C	* 26V11CT4D	11M52A2	014-9803	007	7C		(STATOR)	11.8	10-2	0.086	0.18	17-0
ORQUE	1a-A	26V11TX4b	11M9D2	519-5598 972-6650	DEF 1	148/6 6A	1.732	R1 R2	26	26	0.280	1-10	7.7
TRANSMITTERS	1a-C	* 26V11TX4C	11M9Y2	014-9802	006	6D		(ROTOR)	26	26	0-280	1-00	7.7
TORQUE DIFFERENTIAL TRANSMITTER	1a-A		11M5A2		-	-	1.789	S1 S2 S3 (STATOR)	11-8	10-2	0.375	1-00	4.7
TORQUE	1b-B	26V11TR4b	11M4E2	519-5597 972-6676	DEF	148/5 5A	1.732	R1 R2	26	26	0.280	1.10	7.7
RECEIVERS	1a-C	* 26V11TR4C	11M4N2	014-9801	005	5C		(ROTOR)	26	26	0.280	1.00	7.7
	1 10		DI	ESCRIPTION			TO SERVICE			PRIMA	ARY		

Drawing & Hardware Detail Ref SYNCHRO FUNCTION MILITARY RATED TYPE NATO LENGTH NO LOAD D.C. NUMBER 5990-99-SPECIFICATION DEF STAN M TERMINALS ESISTANCE INPUT Volts Ohms 59-27(2) 20708 11CX4c 1a-A 11M1G1 519-5601 DEF 148/2 115 115 0.031 0.61 320 CONTROL R1 R2 972-6651 1.732 TRANSMITTERS (ROTOR) * 11CX4E 1a-C 11M1X1 014-9807 002 2C 115 0.031 0.61 320 CONTROL 1a-A 11CDX4a 11M3B2 519-5603 DEF 148/81 90 78 0.049 0.73 200 S1 S2 S3 DIFFERENTIAL TRANSMITTERS 972-7576 81A 1.789 (STATOR) 1a-C * 11CDX4B 11M3M1 081 90 014-9811 81C 0.049 0.73 200 78 11CT4c 11M2G1 519-5594 **DEF 148/1** 90 78 0.29 600 1a-A 0.018 † CONTROL S1 S2 S3 972-7619 1.732 TRANSFORMERS (STATOR) 1a-C * 11CT4E 11M52A1 014-9806 001 1D 90 78 0.018 0.31 600 1a-A 11TX4b 11M9D1 519-5599 **DEF 148/4** 115 115 0.060 1-10 160 TORQUE R1 R2 1-732 972-6670 014-9810 44 TRANSMITTERS (ROTOR) 1a-C * 11TX4C 004 11M9Y1 4C 115 0.060 1-00 160 115 TORQUE S1 S2 S3 DIFFERENTIAL 11M5A1 90 0.09 135 1a-A 78 1.50 (STATOR) TRANSMITTER 11TR4b 1b-B 11M4E1 519-5596 **DEF 148/3** 115 115 0.060 1-10 160 R1 R2 TORQUE 972-6675 1.732 (ROTOR) RECEIVERS * 11TR4C 003 1a-C 11M4N1 014-9809 115 0.060 160 115 1.00

115V

26V

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STANDARD HARDWARE SUPPLIED WITH EACH INSTRUMENT											
Item	Type No	Detail Ref									
Clamp Assembly	F500/1	A-B-C									
Shaft Nut	F500/11	A-C									
The second secon											
(Small shaft)	F500/37	В									
	F500/10A	A									
Drive Washer (Brass)	F500/10B	С									
Drive Washer (Small shaft)	F500/38A	В									
Terminal Lug	F3384	A-B-C									

Denotes that the Synchro is on the British Qualified products list to specification DEF STAN 59-27 (PART 2). It is also certified as conforming to NATO Electronics Parts Recommendations for Standardisation of Synchros (N.E.P.R. No. 22) which refers to USA Specification MIL-S-20708C. It is preferred for defence applications. Qualification is subject to renewal every four years.

† The voltage gradient for Control Transformers is 0·39 volt/degree (26V) and 1·0 volt/degree (115V).

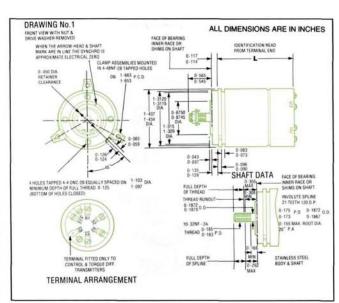
TERMINALS	SECON NO L OUT Volts	OAD	D.C. RESISTANCE Ohms	Zro	NOMINAL IMP	EDANCE ohms Zso	Zss	Stator	RROR mins Rotor Rece	iver f	m\ RESID Fund	,	MI TO GR	MANCE NIMUM DRQUE ADIENT I degree oz in				NIS	ING
S1 S2 S3	11-8	4.5	7.1	34+j265	51+j21	7·7+j45	8 · 7+j3 · 2	7		J I II	12	19	-3.000	a careatra	-				4.300
(STATOR)	11-8	4.5	7.1	34+j265	51+j21	7·7+j45	8 · 7 + j3 · 2	7			12	19							
R1 R2 R3		5.7	15-9	17·6+j86	20·7+j8·7	12·2+j75	17·5+j8·5	10	10		17	26							
(ROTOR)	11-8	5.7	15-9	17-6+j86	20-7+18-7	12-2+175	17·5+j8·5	7	7		17	26							
Security and	22.5	6	80	130+j716	151+j73-5	20+j128	27+j13·8	7	315		15	18	1			1			
R1 R2 (ROTOR)	22.5	6	80	130+j716	151+j73-5	15/1	27+j13-8	7			15	18							
		3.8	2.9	13.7+1114	19·4+i8·7		3-3+j1-3	7					0.61	0.0085	25	38	40		
S1 S2 S3 (STATOR)		3.8	2.9	13-7+i114	155 15 4 567	3-1+j19-4	3-3+i1-3	7					515A	0.008	25	38	40		
	10000	3.0	5.9	13.7+[114	19-4+10-7	3.1+(19.4	3.3+11.3	,	_			_	0.33	0.000	23	30	40	-	
R1 R2 R3 (ROTOR)	11-8	6.5	6.3			6 · 75+j30		10	10				0.3	0.0042					
S1 S2 S3	11-8	3.8	2.9	13·7+j114	19·4+j8·7	3·1+j19·4	3·3+j1·3	7	6	0			0-61	0-0085	25	38	40	1.5	2.5
(STATOR)	11-8	3.8	2.9	13-7+j114	19-4+j8-7	3-1+j19-4	3-3+j1-3		6	0			0.58	0.0085	25	38	40	1	2
TERMINAL		LOAD TPUT Phase lead	D.C. RESISTANCE Ohms nom	Zro	NOMINAL IMP Zrs	EDANCE ohms Zso	Zss	E Stator	RROR mins Rotor Rece	eiver	m\ RESID Fund	v	MI			IMUM INUOUS displace- ment deg		NIS	CHRO- SING Secs
S1 S2 S3	90	4.5	348	550+j4070	725+j307	330+j2080	387+j147	7			45	75							
(STATOR)	90	4.5	348	550+j4070	725+j307	330+j2080	387+j147	7			45	75							
R1 R2 R3	90	4.7	450	450+j1930	487+j200	242+j1690	421+j211	10	10		59	94			- 1.				
(ROTOR)	90	4.7	450	450+j1930	487+j200	242+j1690	421+j211	7	7		60	90							
R1 R2	57-3	4.5	350	510+j3020	535+j302	700+j4900	900+j515	7			30	60				- 3			
(ROTOR)	57.3	4.5	350	510+j3020	535+j302	700+j4900	900+j515	7			32	60							
(- T. 1.050	6	135	285+j2140	370+j159	175+j1090	191+j76	7				- 300	0.61	0.0085	25	38	40		
	90				370+i159	175+j1090	191+j76	7					0-61	0.0080	25	38	40		
S1 S2 S3	All Control	6	135	285+i2140				100					No. of the last	- 0000	10000	-			
S1 S2 S3 (STATOR)	90	6	135 310	285+j2140	0,0,100	180+j1030		10	10				0-3	0.0042					
S1 S2 S3 (STATOR)	90			285+j2140 285+j2140			191+i76	10	10	0		int.		0.0042	25	38	40	1.5	2.



26V & 115V, 60Hz & 400 Hz MIL-S-20708 DEF 148 DEF-STAN 59-27 (PART 2)

AMBIENT TEMPERATURE RANGE: -55° C to +125° C **-55° C to +150° C 400 Hz: Weight 200g (7 oz) Rotor Inertia 10g cm² (0-055 oz in²) Friction Torque 3-6g cm (0-05 oz in) (Not applicable to Torque Receivers)

60 Hz: Weight: 340g (12 oz) Rotor Inertia 22g cm² (0·12oz in²) Friction Torque 3·6g cm (0·05oz in) (Not applicable to Torque Receivers) 15M9D1 & 15M9E1 22g cm (0·3oz in)



				DES	CRIPTION						PRIMA	RY		
	SYNCHRO FUNCTION	Drawing & Hardware Detail Ref	TYP DESIGNA Military		NATO NUMBER 5990-99-	MILIT SPECIFIC DEF STAN 59-27(2)		LENGTH (Dim·L) in inches max	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANCE Ohms nom
	CONTROL TRANSMITTERS	1-A	15CX4b	15M1G1	519-5608 972-6686	DEF 14	14A	1-640	R1 R2 (ROTOR)	115	115	0.082	1 - 41	96
	- INANOMITTENS	1-B	* 15CX4D	15M1V1	014-9812	014	14E	1	(1101011)	115	115	0.085	1 - 41	96
	CONTROL DIFFERENTIAL	1-A	15CDX4b * 15CDX4D	15M3B1	519-5610 972-6666	DEF 14	16A	1 640	S1 S2 S3 (STATOR)	90 90	78	0.090	1.60	108
	TRANSMITTERS	1-B	53925 65 600	15M3H1	014-9815		16D	1 - 640		2000	78	0.090	1 · 34	108
	† CONTROL	1-A	15CT4b	15M2E1	519-5605 972-6661	_ DEF 14	18/15 15A		S1 S2 S3	90	78	0.010	0.200	820
	TRANSFORMERS	1-B 1-B	* 15CT4C 15CT4c	15M2P1 15M2H1	014-9814	015	15E 15D	1.640	(STATOR)	90 90	78 78	0·010 0·010	0·200 0·200	
•	TORQUE TRANSMITTER	1-A	15TX4b	15M9C1	972-6671	See N	ote 1	1-640	R1 R2 (ROTOR)	115	115	0.200	3-1	40
	TORQUE DIFFERENTIAL	1-A	15TDX4b	15M5B1	519-5612 972-6679	DEF 14	48/17 17A	1-640	S1 S2 S3	90	78	0.215	3.5	40
	TRANSMITTERS	1-B	* 15TDX4C	15M5D1	014-9816	017	17D	1-640	(ROTOR)	90	78	0.215	3.5	40
	TORQUE RECEIVERS	1-A 1-A	15TR4C	15M4D1 15M4D2	972-0182 523-3862	DEF 148	/19 19A —	1 - 640	R1 R2 (ROTOR)	115 26	115 26	0·19 0·90	3·4 3·25	40 2·15
	-			DESC	RIPTION						PRIMAR	Y		-
	SYNCHRO FUNCTION	Drawing & Hardware Detail Ref	TYP DESIGN Military		NATO NUMBER 5990-99-	MILITARY SPECIFICATI DEF STAN 59-27(2)		LENGTH (Dim·L) in inches max-	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANCE Ohms nom
	CONTROL TRANSMITTER	1-A	15CX6b	15M1H1	972-7593	-	20A	2 · 391	R1 R2 (ROTOR)	115	115	0-56	2.4	550
	CONTROL DIFFERENTIAL TRANSMITTER	1-A	15CDX6b	15M3G1		DEF 148/2	2	2 · 391	S1 S2 S3 (STATOR)	90	78	0-038	0-63	500
z	† CONTROL TRANSFORMER	1-A	15CT6b	15M2N1		DEF 148/2	1	2 - 391	S1 S2 S3 (STATOR)	90	78	0-013	0 - 21	1300
	-2000000	1-A	See Note 1	15M9D1						See N	lote 2			
	TORQUE TRANSMITTERS	1-A 1-A	See Note 1 See Note 1	15M9E1 * * 15M9F1		See Note 1		2-391	R1 R2 (ROTOR)	115 115	115 115	0·2 0·2	1·7 1·7	450 450
	TORQUE RECEIVER	1-A	15TR6a	15M4H1	972-0183	DEF 148/2	3 23A	2-391	R1 R2 (ROTOR)	115	115	0.2	3.1	400

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SUPP	D HARDV NORMALL LIED WITH ISTRUME	Y
Item	Type No	Detail Ref
Clamp Assembly	F500/1	A-B
Shaft Nut	F500/11	А-В
Drive Washer (Aluminium)	F500/10A	A
Drive Washer (Brass)	F500/10B	В
Terminal Lug	F3090	A-B

* Denotes that the Synchro is on the British Qualified products list to specification DEF STAN 59-27 (PART 2). It is also certified as conforming to NATO Electronics Parts Recommendations for Standardisation of Synchros (N.E.P.R. No. 22) which refers to USA Specification MIL-S-20708C. It is preferred for defence applications. Qualification is subject to renewal every four years. † Voltage Gradient for Control Transformers is 1 volt/degree.

SPECIAL NOTES

NOTE 1: 15M9C1, 15M9D1 and 15M9E1 are basically designed to MIL-S-20708A. 15M9D1 & E1 are suitable for atomic reactor use as control rod indicator transmitters in ambients up to 150 °C and regions of limited radio activity. 15M9F1 is basically designed to MIL-S-20708A and is intended for use as a transmitter with 15TR6a. NOTE 2: Details as for 15M9E1, but spiral ligaments limiting rotation to 450 °.

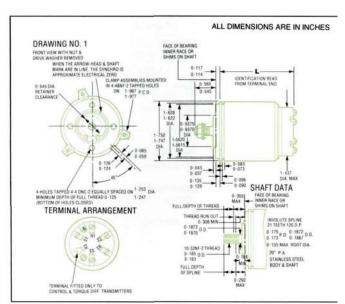
	SECON	DARY										F	ERFORM	MANCE					
TERMINALS	NO L OUT Volts		D.C. RESISTANCE Ohms nom	Zro	NOMINAL IMP	EDANCE ohms Zso	Zss		RROR m Rotor	ins Receiver		nV IDUAL Total	TOP	RQUE DIENT degree oz in	CONT	XIMUM TINUOUS displace- ment deg	PULL-OUT TORQUE g cm	NIS	ING
S1 S2 S3	90	3.6	83	179+j1400	217+j125	100+j775	112+j63	6		-	40	90					- 11		
(STATOR)	90	3.6	83	179+j1400	217+j125	100+j775	112+j63	6			32	60							
R1 R2 R3	90	5.2	139	159+j1060	190+j125	129+j917	164+j111	6	6		60	90				108			
(ROTOR)	90	5.2	139	159+j1060	190+j125	129+j917	164+j111	6	6		32	60							
	57-3	4.2	530	837+j5170	943+j589	1020+j8330	1500+j982	6			40	60							
R1 R2 (ROTOR)	57·3 57·3	4·2 4·2	530 530	837+j5170 837+j5170	943+j589 943+j589	1020+j8330 1020+j8330		6			32 32	60 60				J.		1	
S1 S2 S3 (STATOR)	90	2.5	42	100+j955	96+j68	65+j493	48+j33	6			120	220	2.2	0.03	22	10	85		
R1 R2 R3	90	4-0	94	100+j503	107+j62	50+j418	88+j60	8	8		-	-	0.79						
(ROTOR)	90	4-0	94	100+j503	107+j62	50+j418	88+j60	8	8		-	_	0.79	0-011					
S1 S2 S3 (STATOR)	90 11-8	5·0 4·0	42 0·83	100+j995 5+j47	96+j68 —	65+j493 1 · 1+j8 · 3	48+j33 0·9+j0·4	6		45 45	=	=	2·2 1.70	0·03 0·23	22 22	10 10	85 85	1	2 2
TERMINALS		OAD PUT Phase lead	D.C. RESISTANCE Ohms nom	Zro	NOMINAL IMP Zrs	PEDANCE ohms Zso	Zss		RROR n Rotor	nins Receiver		mV IDUAL Total	MIN	RMANCE IMUM RQUE IDIENT degree oz in	MA CON	XIMUM TINUOUS displace- ment deg	PULL-OUT TORQUE g cm	NIS	CHRO SING E secs
S1 S2 S3 (STATOR)	90	15	470	628+j2210	1170+j299	367+j1190	630+j143	7	V		75	110							
R1 R2 R3 (ROTOR)	90	10	940	780+j2625	1114+ 270	435+j2270	930+j830	8	8		75	125							
R1 R2 (ROTOR)	57 · 3	9-0	900	970+j3800	1430+j409	1140+j6240	2280+j836	6			60	90	3						
S1 S2 S3 (STATOR)	90 90	14 14	390 390	500+j2000 500+j2000	800+j180 800+j180	300+j1300 300+j1300	450+j100 450+j100	10 6			_	=	2.2 2·2	0·03 0·03	70 70	33 33	95 95		
S1 S2 S3 (STATOR)	90	14	350	502+j2240	885+j194	301+j1400	509+j106	6		45		_	2.2	0.03	70	33	95	1	2



115V 60Hz & 400 Hz MIL-S-20708 DEF-STAN 59-27 (PART 2)

AMBIENT TEMPERATURE RANGE: -55°C to +125°C

Weight 400g (14 oz) Rotor Inertia 29g cm² (0·16 oz in²) Friction Torque 3·6g cm (0·05 oz in) (Not applicable to Torque Receivers)



			DE	SCRIPTION					PRIMA	RY		
SYNCHRO Function	Drawing & Hardware Detail Ref	TYPE DESIGNA Military		NATO NUMBER 5990-99-	MILITARY SPECIFICATION DEF STAN MIL 59-27(2) 2070		TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANC Ohms nom
CONTROL TRANSMITTERS	1-A 1-B 1-B	18CX4b * 18CX4d * 18CX4D	18M1B2 18M1C1 18M1D1	519-5614 972-6687 014-9822	DEF 148/28 - 28 - 28 028 28	2 - 388	R1 R1 (R0T0R)	115 115 115	115 115 115	0·11 0·11 0·11	1·32 1·32 1·32	25 25 25
CONTROL DIFFERENTIAL TRANSMITTERS	1-A 1-B	18CDX4b * 18CDX4C	18M3B1 18M3D1	519-5618 972-6667 014-9825	DEF 148/30 - 30 030 30		S1 S2 S3 (STATOR)	90 90	78 78	0·128 0·128	1·21 1·21	50 50
† CONTROL TRANSFORMERS	1-A 1-B 1-B	18CT4b * 18CT4e * 18CT4C	18M2B2 18M2C1 18M2E1	519-5616 972-6662 014-9824	DEF 148/29 - 29 - 29 029 29	2 - 388	S1 S2 S3 (STATOR)	90 90 90	78 78 78	0·0065 0·0070 0·0070	0.07	850 850 850
TORQUE DIFFERENTIAL TRANSMITTER	1-B	* 18TDX4C	18M5C1	014-9826	031 31	2 · 388	S1 S2 S3 (STATOR)	90	78	0 - 45	4.5	11
TORQUE RECEIVERS TRANSMITTERS	1-A 1-B	18TR4b 18TRX4a	18M4F1 18M4L1	972-6677 547-0891	DEF 148/32 32 - 32		R1 R2 (ROTOR)	115 115	115 115	0·43 0·40	4·0 4·0	9·5 9·5

			DES	SCRIPTION						PRIMA	RY		
SYNCHRO FUNCTION	Drawing & Hardware Detail Ref	TYF DESIGN Military		NATO NUMBER 5990-99-	MILITA SPECIFIC DEF STAN 59-27(2)		LENGTH (Dim·L) in inches max-	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANC Ohms nom
CONTROL	1-A	18CX6b	18M1B1	519-5613 972-6658	DEF 14	33A		R1 R2	115	115	0.040	1-11	520
TRANSMITTERS	1-B 1-B	* 18CX6c * 18CX6C	18M1C2 18M1D2	014-9828	033	33B 33C	2.388	(ROTOR)	115 115	115 115	0·040 0·040	1 · 11 1 · 11	520 520
CONTROL	1-A	18CDX6b	18M3B2	519-5619	DEF 14		0.000	S1 S2 S3	90	78	0.052	1 - 45	572
DIFFERENTIAL TRANSMITTERS	1-B	* 18CDX6D	18M3D2	972-6668 014-9831	036	36A 36C	2-388	(STATOR)	90	78	0.052	1 - 45	572
† CONTROL	1-A	18CT6b	18M2B1	519-5617 972-6663	DEF 14	8/34 34A	2.388	S1 S2 S3	90	78	0-017	0.45	2160
TRANSFORMERS	1-B	* 18CT6D	18M2E2	014-9829	034	340	2.300	(STATOR)	90	78	0.017	0.45	2160
TORQUE TRANSMITTER	1-A	18TX6a	18M9B1	972-6672	DEF 148/3	7 37A	2.388	R1 R2 (ROTOR)	115	115	0 · 100	4	245
TORQUE RECEIVERS TRANSMITTERS	1-A 1-B 1-A	18TRX6a 18TRX6b ‡	18M4E1 18M4N1 18M4E2	972-6683	= 1	35A 35C	2.388	R1 R2 (ROTOR)	115 115 115	115 115 115	0·105 0·105 0·094	4	245 245 365

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STANDARD HARDWARE ITEMS NORMALLY SUPPLIED WITH EACH INSTRUMENT												
Item	Type No											
Clamp Assembly	F500/1	A-B										
Shaft Nut	F500/11	A-B										
Drive Washer (Aluminium)	F500/10A	A										
Drive Washer (Brass)	F500/10B	В										
Terminal Lug	F3090	A-B										

* Denotes that the Synchro is on the British Qualified products list to specification DEF STAN 59-27 (PART 2). It is also certified as conforming to NATO Electronics Parts Recommendations for Standardisation of Synchros (N.E.P.R. No. 22) which refers to USA Specification MIL-S-20708C. It is preferred for defence applications. Qualification is subject to renewal every four years. † The voltage gradient for the Control Transformers is 1 volt/degree. ‡ Designed to operate at 50Hz.

DEDECORMANCE

NO LI	DAD	D.C. RESISTANCE Ohms	Zro	NOMINAL IMPE	EDANCE ohms Zso	Zss	EF Stator		ceiver F		AL	MINI TOR GRAI	MUM QUE DIENT	MAX	INUOUS	PULL-OUT TORQUE g cm	RON	ACH- ISING secs
	lead	nom										g cm	oz in	g cm	ment deg	Jil.	30 °	- 175°
90	1	38	78+j1210	78+j81	52+j598	40+j39	6			50 9	10							
90 90	1	38 38	78+j1210 78+j1210	78+j81 78+j81	52+j598 52+j598	40+j39 40+j39	6											
90	3	45	65+j669	72+j71	63+j623	65+j64	6	6	9	40 7	5							
90	3	45	65+j669	72+j71	63+j623	65+j64	6	6	9	40 7	5							
57 - 3	2.5	390	800+j7770	745+j782	1360+j12600	1240+j1250	6			30 4	15						tre.	
57·3 57·3	2·5 2·5	390 390	800+j7770 800+j7770	745+j782 745+j782	1360+j12600 1360+j12600	1240+j1250 1240+j1250	6											
90	3	14	20-8+j206	21 · 1+j22 · 1	17+j183	18·3+j19·9	8	8	,	Not appli	able	4-3	0.06					
90	1.5	10-5	25+j370	25+j25	16+j180	12+j12	5		45 1	Not applie	cable	7-2	0-1	104	12	455	1	2
90	1.5	10-5	25+j370	25+j25	16+j180	12+j12	8		45	50 1	00	7.2	0-1	104	12	455	1	2
NO L	DAD PUT		negovi								AL	MIN TOF GRA	IMUM RQUE DIENT	MA	INUOUS	PULL-OUT TORQUE	RON	NCH- ISING
Volts	Phase	nom	Zro	Zrs	Zso	Zss	Stator	Rotor Re	eceiver l	Fund			gree oz in			g cm		- 175
90	10	623	605+j3130	1380+j451	510+j1580	740+j150	8		1	65 1	15		, III		339			
90 90	10 10	623 623	605+j3130 605+j3130	1380+j451 1380+j451	510+j1580 510+j1580	740+j150 740+j150	8											
90	17	867	717+j1850	1130+j315	465+j1490	885+j308	8	8	10	80 1	00		AL				The same	
90	17	865	717+j1850	1130+j315	465+j1490	885+j308	7	7		60 1	00							
57-3	18	1050	1050+j3280	1880+j611	1690+j4800	2830+j848	6		1	30	60							
57-3	18	1050	1050+j3280	1880+j611	1690+j4800	2830+j848	6			25	45							
90	14	300	335+j1270	686+j210	256+j916	379+j81	6		,	Not appli	cable	3.6	0.05	134	37	172		
90	14	300 300	335+j1270 335+j1270	686+j210 686+j210	256+j916 256+j916	379+j81 379+j81	6			Not appli	cable 00	3-6	0-05	134 134	37 37	172 172	1	2 2
	90 90 90 90 90 90 90 90 90 90 90 90 90 9	Phase lead	NO LOAD Phase Ph	NO LOAD OUTPUT RESISTANCE Ohms nom	NO LOAD RESISTANCE Value Value	NO LOAD OUTPUT RESISTANCE Inches Inche	NO LOAD OUTPUT RESISTANCE Phase Ohms nom No No No No No No No	NO LOAD OUTPUT Phase Ohms Phase Ohms NO MINAL IMPEDANCE ohms Phase Ohms NO MINAL IMPEDANCE ohms NO MINAL IMPEDANCE ohms NO MINAL IMPEDANCE ohms NO MINAL Ohm NO LOAD OUTPUT NO LOAD OUTPUT RESISTANCE OUTPUT Resistance Output Output Phase Ohms No MINAL Ohm No LOAD OUTPUT Resistance Ohms No LOAD OUTPUT Resistance Ohm No LOAD OUTPUT Resistance Ohms No LOAD OUTPUT Resistance Ohm No LOAD OUTPUT OUTPUT Resistance Ohm No LOAD OUTPUT OHM OH	NO LOAD OLO Olo	NO LOAD OUTPUT Phase Ohms EastSTANCE Ohms East Ohms Oh	NO LOAD OUTPUT RESISTANCE Zro Zrs NOMINAL IMPEDANCE ohms Zss Stator Rotor Receiver Fund T	NO LOAD Place Pl	NO 1-10 No 1-10 No No No No No No No N	No No No No No No N	NO D.C. OUTPUT RESISTANCE STANCE S	NO OAD OLO DUTPUT RESISTANCE Plane Plane	No No No No No No N	No Output Plane Plan

CECONDARY

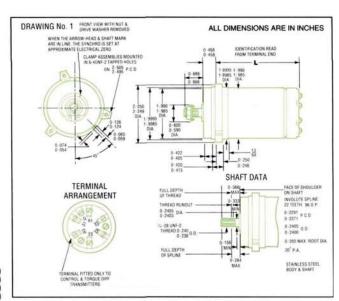


115V, 60Hz & 400 Hz MIL-S-20708 DEF 148 DEF-STAN 59-27 (PART 2)

AMBIENT TEMPERATURE RANGE: -55°C to +125°C

Weight 850g (30 oz) Rotor Inertia 130g cm² (0·71 oz in²) Friction Torque 14g cm (0·2 oz in) (Not applicable to Torque Receivers)

DESCRIPTION



DDIMADY

			DESC	CRIPTION							PRIMARY		
SYNCHRO Function	Drawing & Hardware Detail Ref	TYF DESIGN Military		NATO NUMBER 5990-99-		TARY ICATION MIL-S 20708/	LENGTH (Dim·L) in inches max·	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANCE Ohms nom
CONTROL	1-A	23CX4b	23M1C1	519-5633 971-7209	DEF 1	48/45 I 45A	3-160	R1 R2	115	115	0-245	2.94	15-5
TRANSMITTERS	1-B	* 23CX4D	23M1H1	014-9832	045	45A 45D	3-100	(ROTOR)	115	115	0.245	2.95	15-5
CONTROL	1-A	23CDX4b	23M3B1	519-5622 971-8487	DEF 1	48/47 I 47A	3-410	S1 S2 S3	90	78	0.284	2.9	18
TRANSMITTERS	1-B	* 23CDX4C	23M3E1	014-9834	047	47C		(STATOR)	90	78	0.285	2.9	18
CONTROL	1-A	23CT4b	23M2B1	519-5626 971-8488	DEF 1	48/46 I 46A	3-160	S1 S2 S3	90	78	0.0058	0.071	730
TRANSFORMERS	1-B	* *23CT4C	23M2E1	014-9833	046	46C	DECIMENT.	(STATOR)	90	78	0.0057	0.071	730
TORQUE	1-A	23TX4b	23M9C1	519-5634	DEF 1	48/44		R1 R2	115	115	0-719	6.5	2.8
TRANSMITTERS	1-A		**23M9C3				3-160	(ROTOR)	115	115	0-800	4.5	3-4
TORQUE DIFFERENTIAL TRANSMITTER	1-A		‡ 23M5B1	972-6681	-	-	3-410	S1 S2 S3 (STATOR)	90	78	0.950	5.2	4-3
TORQUE RECEIVERS	1-A 1-B	23TR4b * 23TRX4A	23M4D1 23M4F2	519-5624 014-9836	DEF 1 050	48/50 50C	3-160	R1 R2 (ROTOR)	115 115	115 115	0·719 0·720	6·5 4·6	2·8 2·8
			DES	CRIPTION							PRIMARY	ž.	
SYNCHRO Function	Drawing & Hardware Detail Ref	TYI DESIGN Military		NATO NUMBER 5990-99-		ITARY ICATION MIL-S 20708/	LENGTH (Dim·L) in inches max-	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANC Ohms nom
CONTROL	1-A	23CX6c	23M1C2	519-5632	DEF 1	48/52		R1 R2	115	115	0.080	1 - 60	195
TRANSMITTERS	1-B	* 23CX6D	23M1H2	972-6659 014-9837	052	52A 52C	3-160	(ROTOR)	115	115	0-080	1.74	184
CONTROL	1-A	23CDX6b	23M3B2	519-5623	DEF 1	1,48/54	HIM	S1 S2 S3	90	78	0.090	1-60	255
DIFFERENTIAL TRANSMITTERS	1-B	* 23CDX6C	23M3E2	972-6669 014-9839	054	54A 54C	3-410	(STATOR)	90	78	0.090	1.82	255
t CONTROL	1-A	23CT6c	23M2B2	519-5625	DEF	148/53	27062	S1 S2 S3	90	78	0-0185	0.45	1740
TRANSFORMERS	1-B	* 23CT6D	23M2E2	014-9838	053	53A 53C	3-160	(STATOR)	90	78	0-0185	0.50	1740
TORQUE TRANSMITTER	1-A	23TX6b	23M9C2	972-6674	DEF 14	8/51 51A	3-160	R1 R2 (ROTOR)	115	115	0.23	6-0	74
TORQUE DIFFERENTIAL TRANSMITTER	1-A	23TDX6b	25M5B2	972-6682	_	55A	3-410	S1 S2 S3 (STATOR)	90	78	0.20	5.0	113
TORQUE	1-A	23TRX6a	23M4C1	519-5629	DEF	148/56	2 100	R1 R2	115	115	0.23	6.0	74
RECEIVER		* 23TRX6B		972-6684	_	56A	3.160	(ROTOR)					

60 Hz

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EACH I	NSTRUME! Type No	To be a second
Shaft Nut	F500/53	A-B
Drive Washer (Aluminium)	F500/32A	A
Drive Washer (Brass)	F500/32B	В
Terminal Lug	F3090	A-B

* Denotes that the Synchro is on the British Qualified products list to specification DEF STAN 59-27 (PART 2). It is also certified as conforming to NATO Electronics Parts Recommendations for Standardisation of Synchros (N.E.P.R. No. 22) which refers to USA Specification MIL-S-20708C. It is preferred for defence applications. Qualification is subject to renewal every four years. † The voltage gradient for Control Transformers is 1 volt/degree.

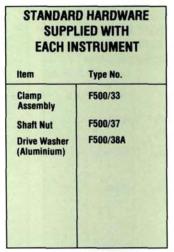
** Basically designed to the requirements of MIL-S-20708A. ‡ Basically designed to the requirements of MIL-S-20708A and DEF 148.

1 1 1 1 1 1 1	SECON	DARY	+11										PERFOR	1000				
TERMINALS	NO LI OUT Volts		D.C. RESISTANCE Ohms nom	Zro	NOMINAL IMF Zrs	PEDANCE ohms Zso	Zss	Stator	RROR m Rotor	ins Receiver	m RESID Fund		TO	IMUM RQUE DIENT degree oz in		CIMUM INUOUS displace- ment deg	PULL-OUT TORQUE g cm	SYNCH- RONISING TIME sect 30° - 17
S1 S2 S3	90	1.8	11.8	31+j530	31+j36	15+j263	15·7+j17·7	8			40	60						
(STATOR)	90	1.8	11.8	31+j530	31+j36	15+j263	15·7+j17·7	6			32	48						
R1 R2 R3	90	3	19	26+j310	27+j30	24+j280	24·7+j27·2	7	7		40	75						
(ROTOR)	90	3	19	26+j310	27+j30	24+j280	24·7+j27·2	7	7		30	60						
R1 R2	57.3	2	330	750+j8570	660+j812	1230+j14300	1100+j1360	6	lie, i		30	60						
(ROTOR)	57-3	2	330	750+j8750	660+j812	1230+j14300	1100+j1360	6			20	45						
S1 S2 S3	90	1	3.7	14+j225	8·7+j11	8 · 5+j110	4 · 2+j5 · 3	6			-	-	18	0.25	290	16	1380	
(STATOR)	90	1	3.0	18+j257	8 · 8+j12	10+j126	4 · 3+j5 · 8	6			75	100	17-3	0.24	275	16	1300	
R1 R2 R3 (ROTOR)	90	2	6-0	10+j120	8·2+j11·7	7 · 8+j107	7·3+j10·6	8	8			Min.	11	0.15				
S1 S2 S3 (STATOR)		1 1	3·7 3·7	14+j225 14+j225	8 · 7+j11 8 · 7+j11	8 · 5+j110 8 · 5+j110	4·2+j5·3 4·2+j5·3	6		45 45	_ 30	150	18 18	0·25 0·25	290 275	16 16	1380 1380	1 2
TERMINALS		OAD	D.C. RESISTANCE Ohms	Zro	NOMINAL IM	PEDANCE ohms Zso	Zss		ERROR m Rotor	nins Receiver		oV DUAL Total	GR/ Fund	IMUM RQUE ADIENT degree oz in	MA	XIMUM FINUOUS displace- ment deg	PULL-OUT TORQUE g cm	SYNCH- RONISING TIME sec 30° - 17
S1 S2 S3	90	6	276	242+j1650	462+j150	211+j954	319+j62	8			40	75						
(STATOR)		6	221	242+j1650	462+j150	211+j954	319+j62	6			30	60						
R1 R2 R3	90	11	315		453+j147	214+j947		8	8	717	65	80			01/8	100	100	BA
(ROTOR)	90	11	315		453+j147	214+j947		8	8		40	65						
R1 R2	57 - 3	14	800	883+j3080	1500+j512	1380+j4790	2370+j791	6		110	40	60	97					
(ROTOR)	57-3	14	800	883+j3080	1500+j512	1380+j4790	2370+j791	6		-	30	45						
S1 S2 S3 (STATOR)		7	103	96+j738	210+j63	78+j445	106+j24	8				all land	8-6	0-12	475	44	700	
R1 R2 R3 (ROTOR)	90	11	129	105+j500	181+j62	85+j415	152+j54	6	6				2.2	0.03				
S1 S2 S3		7	103	96+j738	210+j63	78+j445	106+j24	8		45			8-6	0-12	475	44	700	1 2
	00																	

Size 08 Brushless Synchros

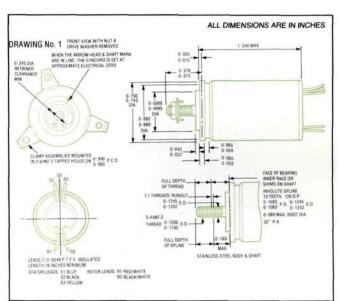


26V 400Hz



AMBIENT TEMPERATURE RANGE: -55°C to +125°C

Weight: 48g (1 · 7 oz) Friction Torque: 2 · 9 g cm (0 · 04 oz in) Rotor Inertia: 1 · 0 g cm² (0 · 0055 oz in²)



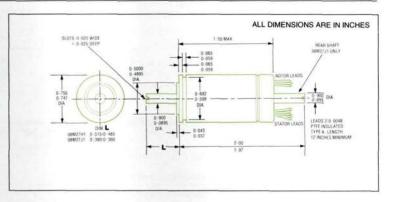
				PRI	MARY				SECON	DARY						PER	FORMA	NCE
SYNCHRO FUNCTION	TYPE DESIGNATION Muirhead	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANCE Ohms Nom.	TERMINALS	OU	LOAD TPUT Phase lead	D.C. RESISTANCE Ohms nom.		NOMINAL EDANCE Ohn Zrs	is Zso	Zss	ERROR mins	RESII Fund	V DUAL Tota
CONTROL TRANSMITTER	08M71A1	R1 R2 (ROTOR)	26	26	0 · 12	2.2	8-0	S1 S2 S3 (STATOR)	11-8	28	60	160+j215	220+j215	80+j80	92+j13	10	20	30
CONTROL TRANSFORMER	08M72A1	S1 S2 S3 (STATOR)	11-8	10.2	0-027	0.053	62	R1 R2 (ROTOR)	22.5	17	500	1100+j1640	1300+j470	75+j400		14	30	40

size 08 tandem synchros



TEMPERATURE Friction Torque: 1 g cm. (0·014 oz in)

RANGE -55° C to 125° C Rotor Inertia: 1 g cm² (0·0055 oz in²)



				PR	IMARY				SECOND	ARY						PERI	FORMA	NCE
SYNCHRO FUNCTION	TYPE DESIGNATION Muirhead	TERMINALS	RATED VOLTS	Volts	NO LOAD INPUT Amps max	Watts max	D.C. RESISTANCE Ohms Nom.	TERMINALS	NO L OUT Volts		D.C. RESISTANCE Ohms nom.		NOMINAL EDANCE Ohn Zrs	ns Zso	Zss	ERROR mins		DUAL Total
CONTROL TRANSFORMER	08M27H1	(STATOR)	11.8	10-2	0.032	0-070	60	(ROTOR)	22-5	6-5	260	410+j2040	470+j180	60+j370	90+j30	15	40	40
PICK-OFF RESOLVER	08M27J1	(STATOR)	15	15	0.053	0.73	277	(ROTOR)		54	122	130+j130	180+j80	280+j200	370+j120	15*		

^{*} Or $1\frac{1}{2}$ % of electrical angle, whichever is greater. Measured over limited angular range of \pm 60°

Size 18 Synchros Indicating Receiver

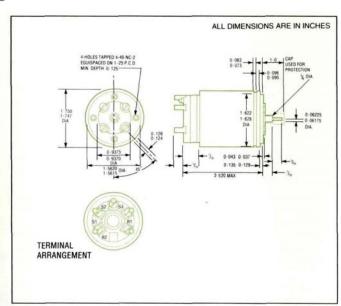


115V 60Hz & 400 Hz

AMBIENT TEMPERATURE RANGE: -55° C to +85° C



Weight 370g (13 oz) Rotor Inertia 2 · 7g cm² (0 · 15 oz in²)



				PRI	MARY ELE	CTRICAL D	ATA			SECONDA	ARY ELECT	RICAL DATA		
TYI DESIGN Muirhead		NATO NUMBER 5990-99	FREQUENCY Hz	TERMINALS	VOLTAGE Volts	CURRENT Amps	IMPEDANCE Ohms	D.C. RESISTANCE Ohms Nom	STATOR VOLTAGE Volts	CURRENT Amps	POWER Watts	IMPEDANCE Ohms	D.C. RESISTANCE Ohms Nom	FOLLOWING ACCURACY Degrees
18R16X	18M23A2	372-7453	60	R1 R2 (ROTOR)	115	0.03	3000+j3800	2500	90	0.03	3.0	3300+j3000	2900	4(spread)
	18M23A1	523-3887	400	R1 R2 (ROTOR)	115	0.03	1500+j3800	3 410	90	0.03	2.0	2200+j3000	2175	4 (spread)

SPECIAL NOTE

These units are low torque receivers for use with size 18 or 23 control transmitters (see pages 10-13). They are designed for pointer indication only and impose little reaction on the transmitter so that, if a number of receivers are operated from one transmitter and one is restrained, the accuracy of the others is not impaired.

Conversion Table

Parameter	Metric	Multiply by	Imperial	Divide by	Metric
	Unit	to convert to	Unit	to convert	Unit
Length					
	mm	0.03937	Inches	25.40	mm
Weight					
	g	0.035274	OZ	28.3495	g
Temperature	_				_
•	°C	(°Cx9÷5)+32	°F	(°F-32x5)÷9	°C
Speed		•		•	
•	rad/s	9.54930	rpm	0.10472	rad/s
Force					
	Ν	3.59572	OZ	0.2781	N
Torque					
4	Nm	0.73731	lbft	1.355628	Nm
	Nm	141.5636	ozin	0.00706	Nm
	gcm	0.01388	ozin	72.0461	gcm
Torque Sensit	tivity				
	Nm/A	0.73731	lbft/A	1.35628	Nm
	Nm/A	141.5636	ozin/A	0.00706	Nm
	gcm/A	0.01388	ozin/A	72.0461	gcm/A
Motor Consta	nt				
	Nm/√W	0.73731	lbft/√W	1.35628	Nm/√W
Damping Fact	tor				
. 0	Nm/rad/s	0.73731	lbft/rad/s	1.35628	Nm/rad/s
Voltage Sensi					
0	V/rad/s	1	V/rad/s	1	V/rad/s
Rotor Inertia					
	kgm2	23.7303	lbft2	0.04214	Kgm2
-					

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